NLE'S

<u>Goal</u> A single encoder for diverse 2D & 3D tasks



estimation

(3D reconstruction, pose regression, etc.) DINO-v2

Multi-HMR

MASt3R:



[UNIC] UNIC: Universal Classification Models via Multi-teacher Distillation. Sarıyıldız et al. ECCV'24. [MASt3R] Grounding image matching in 3D with MASt3R. Leroy et al. ECCV'24.

Distilling a UNiversal Encoder from Heterogeneous 2D and 3D Teachers

HETEROGENEOUS $\sum ATA$

Multi-teacher distillation

 Transformer projectors ✓ Teacher dropping [UNIC]



18M generic images (subset of original training set) from 3 datasets 500k images from 4 datasets, centered on humans, mainly synthetic 2M real and synthetic images from 12 datasets (indoor scenes, outdoor landmarks, objects, etc.)

+ decoder fine-tuning

Results with a universal encoder 2D vision **3D** vision

	Encoder Arch.	Training ' Data	Training Res.	ADE20k (mIoU ↑)	NYUd (RMSE ↓)	BEDLAM (F1-score ↑)	BEDLAM (PA-PVE \downarrow)	MapFree (AUC ↑)
nodels								
2	ViT-Large	LVD-142M	518	47.7	0.384	-	-	-
MR	ViT-Large	HMR-500K	672	-		95	36.9	
	ViT-Large	MASt3R-1.7M	512	-	-	-	-	91.2
he-art ViT-	Base encoder	rs						
2	ViT-Base	LVD-142M	518	47.3	0.399	86	76.5	89.6
DIO-v2.5	ViT-Base	DataComp-1B	512	50.0	0.718	89	83.2	93.1
	ViT-Base	DUNE-20.7M	336	44.9	0.377	91	68.3	93.7
	ViT-Base	DUNE-20.7M	448	45.6	0.358	94	56.0	94.7

A ViT-Base encoder for MASTER

 Comparable or improved performance Smaller encoder (Vit-B vs. ViT-L originally) State-of-the-art Visual Relocalization (Map-free)

[Multi-HMR] Multi-HMR: Multi-person whole-body human mesh recovery in a single shot. Baradel et al. ECCV'24. [DINOv2] DINOv2: Learning robust visual features without supervision. Oquab et al. TMLR'24.

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✓ Feature standardization



distillation loss

HETEROGENEOUS TEACHERS

MASTER **3D** Foundation model

Multi-HMR

Human Perception model

DINOv2 2D Foundation model

Map-free Reloc. Leaderboard

Method	AUC (VCRE < 45px)	AUC (VCRE < 90px)
i DUNE + MAST3R	0.840	0.943
i MASt3R (Ess.Mat + D.Scale)	0.817	0.933
i interp_metric3d_loftr_3d2d	0.681	0.796





https://github.com/naver/dune







Data Sharing	ADE20K (mIoU↑)	$\begin{array}{c} \mathbf{NYUd} \\ (\mathbf{RMSE} \downarrow) \end{array}$	MapFree (AUC ↑)	$\begin{array}{c} \textbf{BEDLAM} \\ (PA-PVE \downarrow) \end{array}$
No data sharing	41.6	0.426	93.2	68.7
Generic data sharing	40.1	0.416	92.7	71.7
Full data sharing	44.9	0.377	93.7	68.3

Data sharing among teachers

Distil. Data	Proj. Design	ADE20K (mIoU ↑)	NYUd (RMSE ↓)	MapFree (AUC ↑)	BEDLAM (PA-PVE \downarrow)
IN-19K IN-19K	LP TP	42.4 44.9	0.446 0.433	91.4 93.6	83.9 73.5
All	SP	42.3	0.413	92.2	73.1
All	LP	44.7	0.384	91.5	78.2
All	TP	44.9	0.377	93.7	68.3

Distillation data and projector design

Other results

Mothod	Encoder		Co3Dv2↑	RealEstate10K ↑	
		RRA@15	RTA@15	mAA(30)	mAA(30)
DUSt3R	ViT-Large	<u>93.3</u>	88.4	77.2	61.2
MASt3R	ViT-Large	94.6	91.9	81.8	<u>76.4</u>
DUNE	ViT-Base	92.2	<u>90.7</u>	<u>78.8</u>	79.9

Multi-view pose regression

Model	Cityscapes (mIoU ↑)	NYUv2 (mIoU ↑)	ScanNet (mIoU ↑)	Avg. (mIoU ↑)
Pri3D	56.3	54.8	61.7	57.6
MASt3R	58.9	60.2	57.0	58.7
DUNE (no proj.)	65.6	66.1	61.2	64.3
DUNE	70.6	68.2	65.2	68.0

Semantic segmentation

Precision (VCRE < 45px)

64.4%

63.0%

39.9%